

# ME319 Robotic and Vision Systems Lab

## Adept Notes

### Table of contents

Heading	Page #
<b>Adept startup procedure</b>	<b>2</b>
<b>Teach pendant and coordinate systems</b>	<b>2</b>
<b>Manuals and examples</b>	<b>2</b>
<b>The file system and loading, saving files</b>	<b>2</b>
<b>The See editor and debugger</b>	<b>3</b>
Stepping through a program and checking things	3
Program versus monitor functions	3
<b>Locations and moving around</b>	<b>4</b>
<b>User input and output</b>	<b>4</b>
<b>Vision on the Adept</b>	<b>5</b>
Useful vision settings	5
The most useful vision commands	5
Other tips:	5
<b>Example Vision Program</b>	<b>6</b>